



Another EMC resource
from EMC Standards

The Physical Basis of SI, PI and EMC

Updated for 2018 Ver 3.9

Helping you solve your EMC problems

emc6s+c v3.9 CCC

Module 1: The Physical Basis of SI, PI, and EMC



**CHERRY
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**Update
July 2018:
v3.1 to v3.9**

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Change Record: v3.1 to v3.9, 19 July 2018

- Change Record added, as new slide 1.0.1a (this one)
- 'EMC' replaced (where appropriate) by 'SI, PI and EMC' throughout this whole module
- 'Cherry Clough confidential training material' added at the foot of every slide
- New slide 1.0.1b added
- Slide 1.0.3 improved a little
- Old slide 1.1.4 completely replaced by the two new slides 1.1.4 and 1.1.5
- Old slides 1.4.4 - 1.4.8 replaced with mostly new slides 1.4.4 - 1.4.8c
- New slide 1.4.21 added
- New slides 1.5.5a and 1.5.5b added, slides 1.5.6 and 1.5.7 improved
- Old slides 1.6.9 - 1.6.18 and 1.7.6 modified and improved
- Section 10 slides all completely replaced with new ones: 1.10.1 - 1.10.11
- Sections 15 and 16 swapped, renumbered as Sections 16 and 15 respectively
- Title of Section 18 improved (slide 1.18.1)
- Slide 1.18.2a improved
- Title of slide 1.18.4 improved
- Slide 1.18.5 improved
- Twelve new slides 1.18.9a - 1.18.9l added
- Slides 1.18.10 - 1.18.12; 1.18.15; 1.18.17, and 1.18.18 improved
- New slide 1.18.19 added
- Slides 1.19.3 - 1.19.5 updated and improved

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Signal Integrity (SI), Power Integrity (PI) and Electromagnetic Compatibility (EMC) are easy, when you are used to this understanding of electromagnetism

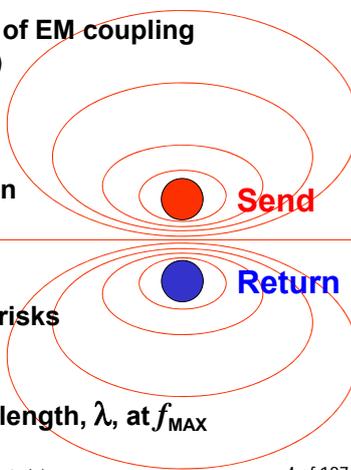
- **Electrical/electronic/radio/digital design, and Maxwell's Equations, are rarely taught in a way that makes SI, PI and EMC easy to achieve in practice...**
 - the approach described in this *almost-maths-free Webinar 1* (and employed through all our “design-guide” webinars) makes SI, PI and EMC design easy...
 - saving a lot of time and money, reducing financial risks, and greatly increasing the chances of success

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Contents

1. Electromagnetic fields, waves, & importance of the return current path
2. Field theory, permittivity, permeability, wave impedance and velocity
3. Near-field and Far-field
4. Three types of analysis (includes Skin Effect)
5. Waveforms, spectra, and ‘accidental antennas’
6. Three parts to every EMC issue, and four types of EM coupling
7. Differential mode (DM) and common mode (CM)
8. The benefits of metal planes
9. Overview of RF emissions
10. ‘Earthing’, ‘grounding’, etc., does not help
11. Non-linearity, demodulation and intermodulation
12. Three interference mechanisms
13. Overview of RF immunity
14. ‘Internal EMC’ and crosstalk
15. Improving profitability while reducing financial risks
16. Introduction to EM Engineering
17. Controlling return currents with metal planes
18. EM Zoning using guidelines based on the wavelength, λ , at f_{MAX}
19. Some useful references and equations



Send
Return

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This module mostly deals with radio frequency (RF) techniques

- because low-frequency SI, PI and EMC issues are easy to understand using normal circuit design techniques
with strays included, see later...
- **This module focuses on the SI, PI and EMC issues that most engineers find difficult...**
 - because of the *apparently* weird things that can happen at frequencies above a few MHz
 - **EMC = Electromagnetic Compatibility: controlling emissions and immunity so radiocommunications and other equipment don't cause or suffer Electromagnetic Interference (EMI)**

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1. The Physical Basis of SI, PI, and EMC

1.1

Electromagnetic fields and waves, and the importance of the return current path

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Electromagnetic (EM) fields

- **Every** voltage/current (power, signal, data, etc. or stray, parasitic, sneak, leak) is **really** a propagating EM wave...
 - guided by send and return conductors *and* the insulators (dielectrics) that surround them (e.g. air, PVC)...
[Strictly: Transverse Electromagnetic: 'TEM' waves]
 - EM waves spread out and create EM fields like ripples spreading out on a pool of water
- Design for good SI, PI and EMC is mostly about controlling fields: so they are **high** where we **want** signals, data and power to be...
 - and **low** where we **don't** want them to be, to control crosstalk, noise, emissions and susceptibility

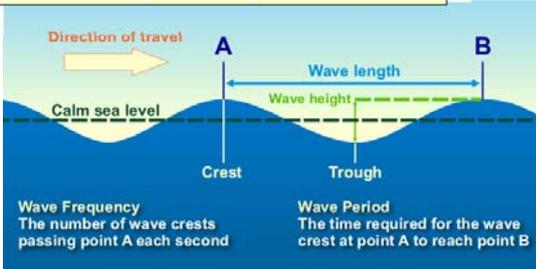


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Of course, a wave has different amplitudes along its path

- So a long conductor *can't* have the same voltage or current over its whole length, at the same time...
 - and this is what causes the 'EMC weirdness'!
 - the ratio between wavelength (λ) and conductor dimension is what is important...
 - we can usually ignore 'wave effects' for any dimension that is $< \lambda/100$ e.g. at 1GHz: $< 3.0\text{mm}$ in air ($\lambda = 300\text{mm}$)
 $< 1.5\text{mm}$ in FR4 ($\lambda = 150\text{mm}$)



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Importance of the return current path

- **All currents *always* flow in closed loops**
all power, signals, data, *and* stray / parasitic / sneak / leaked currents etc...
 - and we can control their E and H field patterns by designing their send and return current paths...
 - which can include flowing through dielectrics (air, plastic, etc.) as “displacement currents”
- **Currents *always* “prefer” to flow in loops with lower overall impedances, at any given frequency...**
 - generally the loops with least enclosed areas, *because they have the most compact E and H field patterns...*
 - i.e. the laws of nature/physics are trying to help us achieve good SI, PI and EMC – we just have to work *with* them!

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Importance of the return current path continued...

- **The current (at any given frequency) will automatically divide up between the available loops, in inverse proportion to their overall loop impedances...**
 - just like DC current divides up between parallel resistors...
 - this generally means that return currents will always “choose” to flow as physically close to their send currents as they can...
 - even if this means flowing through air, or other dielectrics...
 - so we can easily achieve good, cost-effective SI, PI and EMC, by creating send/return loops that have very low overall impedances...
 - for all of the frequencies we want/need to control

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